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1 GENERAL FEATURES of TouchMover-A8

TouchMover-A8® is a compact, rugged and powerful Real-Time Touch-PLC system. It’s a fully featured, IEC-1131 Soft-PLC & SCADA system, capable to manage Control & Supervision applications when connected to your machine-tool or plant. It Brings Automation & Supervision into your project, at a fraction of cost of competitor’s systems, giving you total design control.

In fact, TouchMover-A8® embeds CJB’s “PowerPLC-Bridge” IEC-1131 Real-Time Soft-PLC engine, and so it’s ready to be easily programmed just after you power it up.

Based upon Freescale iMX53 (1 GHz) processor module, it can be provided either with onboard Embedded Linux or with WinCE7® operating systems. It has an ultrabright 7” LCD panel, with LED backlight and dim-to-zero capability, with either 4W resistive touch or PCAP USB touch, and can be delivered in a robust die-cast panel-mount aluminium enclosure with a very nice-looking (and fully customizable) front bezel.

The system can be panel-mounted or placed in a wall-mount enclosure; this latter specifically designed for Building & Home Automation.

It has enhanced connectivity thanks to CANbus interface, Ethernet 10/100 interfaces, 4x USB ports, dual COM serial ports (including isolated RS485 port) and it offers wide local expandability thanks to 25 onboard GPIO’s. There is also a special Battery-back-up SPI RAM onboard (128kB) to save system’s variables with unlimited write cycle capability.

Just power it up, connect to CJB’s POWERPLC-Bridge® IEC-1131 development system, design your control application, add your HMI project (e.g.: using our support with QT-Libraries), download the whole project to the TouchMover-A8, debug it in real-time... and you’re done. You’ll get your powerful control system in a snap and for a fraction of cost of other similar systems.

TouchMover-A8 has been specifically designed to be the perfect solution for:

- Professional food appliances (Ovens, Steam boilers, refrigerators, ice-cream, etc.)
- Vending machines (especially outdoor)
- Parking, ticketing machines (especially outdoor)
- Controllers for building & home automation
- Small & medium sized controllers

Fig. 1 Panel Mount version (left) and Wall Mount version (right)

Fig. 2 Panel Mount version with stylish front bezel
2 SPECIFICATIONS of TouchMover-A8

The inside electronics of the TouchMover-A8 is made of the C2 CPU board:

![The C2 CPU Board (iMX536) inside the TouchMover-A8](image)

This is a powerful ARM-based iMX53 CPU board with the following features:

- Freescale iMX536 (optional: i.MX535)
- 1GB RAM onboard
- 128kB SPI-RAM (static) for permanent storage of data with unlimited write cycles, with battery backup (uses the same battery which keeps the Real Time Clock running)
- UARTS:
  - 1 x RS485/RS-422 optically insulated
  - 1 x RS232 general purpose COM port, not insulated, selectable also as RS422/485
- 2 x USB ports with Type_A dual-stack connector 90º
- 2 x USB 4-pin headers for auxiliary functions (placed inside the pcba)
- 1 x USB OTG for debug purposes
- 2 x Ethernet 10/100 with RJ45 90º connector (1 Ethernet port in the Depopulated version)
- 1 x Micro-SD socket (µSD)
- 1 x SD socket
- 2 x LCD Interfaces:
  - 1 x TTL to support 40pin FPC connector for standard 7” 800x480 with LED backlight (with bonded touch 4W), for two standard versions of LCD panels
  - 1 x LVDS 2ch 24bit to support any kind of LCD panel, up to Full-HD
- 1 x VGA video port
- 1 x 4W touch interface for the touch screen (resistive, 4W)
- 1 x optional 5W/8W resistive touch interface
- 1 x LED Backlight driver for the 7” LCD (which don’t have onboard DCDC), with PWM dimming
- 1 x expansion connector for 3G module piggy-back micro board: this will support one 3G (4G) Mini-PCIe card socket and its USIM card socket
- GPIO: 25 x TTL I/O software selectable as Inputs or Outputs
- 1 x 1-Wire interface (optional, for Dallas-type sensors)
- 1 x CANbus interface
- AUDIO interface:
  - 1 x stereo Line-Out connection
  - 1 x MIC in
  - 1 x stereo Line-In
- Power-Supply: 12~36Vdc wide range power supply with power for 7” LCD panels.
  - The Full-featured board can also provide 3.3Vdc or 5Vdc or 12Vdc for most common LCD panels, and also 5Vdc or 12Vdc for LED driver or CCFL inverter.
- Dimensions: 170mm x 130mm
- Operating System: Embedded Linux, Windows CE7.0
- Certifications: CE. Verified for FCC-B.
3 STARTUP

TouchMover-A8 comes assembled with the C2 CPU module installed inside, and with CJB’s IEC-1131 “PowerPLC-Bridge” Run-Time preloaded. What you need are:

1. One +12Vdc or +24Vdc power source (1A can be ok) to be connected to DC_IN power connector.
2. One PC (Laptop or Desktop) with Windows® O.S. and CJB’s PowerPLC-Bridge IDE (Integrated Development Environment)
3. One crossed RJ45 UTP Ethernet cable (or you can use straight cable to Ethernet switch connected to your LAN). Or connect through LAN switch.
4. After power-up, the system is ready to communicate with PowerPLC-Bridge IDE on the PC. If the TouchMover-A8 is already running an application, you can take control over it, stop, modify, debug, reload and re-run. Otherwise, design your new application, download it into the TouchMover-A8 system, run it, debug it and finally freeze it inside TouchMover-A8 flash memory.
5. If the system has been purchased with the LCD panel, you can also design your HMI application program for the operator interface, run it and test it along with your IEC-1131 application program.
6. If the system is blind, of course you will not be able to run a local HMI application, but you can run HMI anywhere on a PC (PanelPC) or another TouchMover-A8 with LCD, connected through Ethernet to the blind TouchMover-A8, and you’ll have the HMI application remotely executed on the PC or the complete TouchMover-A8 with display.
7. Please refer to IEC-1131 PowerPLC-Bridge manual for how developing a control application for the TouchMover-A8, and refer to CJB for developing an HMI application.

3.1 WALL MOUNT

TouchMover-A8 can be wall-mounted to a special box which will be sealed in a building wall. The matching comes thanks to a special magnet attachment, with also a friendly panning pin for setting the unit perfectly horizontal. Follow the directions in the drawings in the Appendix.

3.2 PANEL MOUNT

TouchMover-A8 can be panel-mounted, which is very useful for Automation applications. The front bezel back side has a special groove where a neoprene O-ring makes tight match to the panel. In this case the unit is pulled against the front panel thanks to rear-side hook-screws. Follow the direction in the drawings in the Appendix.
Fig. 4 Block Schematic
4.1 TOP SIDE VIEW of the CPU board inside (C2)

![Diagram of CPU board]

Fig. 5 Top Side view: shaded areas show features not stuffed in the depopulated version
4.2 BOTTOM SIDE VIEW of the CPU board inside (C2)

Fig. 6 Bottom Side view: shaded area shows items not stuffed because optional upon request.
4.3 OVERVIEW OF ONBOARD FEATURES

4.3.1 RS-485~422 ISOLATED COM1 PORT
The 1st UART (COM1) is RS485/RS422 selectable, and is the main peripheral interface port which will communicate (e.g.: by Modbus-RTU) with external peripherals. This is optically insulated to avoid communication troubles.

4.3.2 RS232/422/485 NON ISOLATED COM2 PORT
The 2nd UART (COM2) is RS232/485/RS422 selectable, and is the general purpose COM port interface. The choice (232/422/485) is made by simple jumper setting (JCOM2 pin header).

4.3.3 CANBUS INTERFACE
The board has a CANbus port, made from the native CANbus interface of the iMX536.

4.3.4 GPIOs
25 TTL (3.3V) GPIOs are wired to a 44-pin header connector, and can be used for an external I/O conditioning board (user’s designed). All GPIOs come from direct GPIO ports of the iMX53x. Furthermore, another GPIO is used for Backlight control, and another one is used for the Buzzer.

4.3.5 LVDS General Purpose Port
The 24Bit 2-Chan LVDS port is provided to interface almost all kinds of commonly available LVDS panels. It can handle up to 2-Channel 24Bits Full-HD.

4.3.6 TTL LCD Port
This 18Bit TTL LCD port is designed to make a snap connection through a 40pin FPC cable for standard 7” 800x480 LCD panels with LED backlight. A suitable LED driver for such panels is provided onboard or can be powered by 5Vdc (most new panels have embedded LED driver).

4.3.7 1-Wire INTERFACE (OPTIONAL)
This is a native interface of the iMX535, available to connect sensors like Dallas or like devices.

4.3.8 Ethernet Ports
There are two 10/100Mb Ethernet Ports (1 only for the depopulated version) available from RJ45 connectors.

4.3.9 Extensive Feature Selectable by Pin-Headers
A number of pin-headers allow easy selection of onboard features, to fit the needs of each application (panel power selection, backlight selection, COM port settings and so on).

4.3.10 Wide Range Power Supply
The board can be powered by 12~36Vdc wide range power supply.
5 JUMPER SETTINGS of the C2
This Chapter details all the onboard Jumpers of the C2 and their settings.

5.1 JUMPER TOPOLOGY of the C2 CPU Board (TOP)
Please always refer to the board TOP topology as from below drawing.

![Diagram](https://via.placeholder.com/150)

*Fig. 7 Topology of the Board (TOP). Lower Side is the Connector Area.*
5.2 JUMPER TOPOLOGY of the C2 CPU Board (BOTTOM)

There are no Jumpers on bottom side.

5.2.1 HOW TO RECOGNIZE PIN 1 (JUMPERS & CONNECTORS)

To recognize Pin 1 of Connectors & Jumpers, the rules are the following:

1) Pin 1 of Jumpers is evidenced by a **bold square** around
2) Pin 1 of Connectors is evidenced by a **bold marking** at side of Pin 1
3) Underneath (BOTTOM Side) Pin 1 has always a **square pad** (others have round pads)
4) In most cases, where there is room, pins are numbered.

![Figure 8: Examples of Silk-Screen figures to recognize Pin 1](image-url)
5.3 POWER SELECTION JUMPERS

Before going to describe the jumper settings, it’s very important to understand the POWER SCHEME of the C2, since there are many jumpers which can affect the behavior of the board, and their settings must be correct, otherwise the board can be damaged.

5.3.1 OVERVIEW OF POWER ROUTING JUMPERS

The image below shows the whole power routing scheme for the C2 FULL version. Main DC power input is from DC_IN connector, which is protected by fuse and by a Varistor. The board is NOT protected against polarity inversion.

The DC_IN supply must be within 12 ~ 36Vdc range.
The first important fact is to know if the board is powered by 12Vdc or by a higher voltage:
- If DC_IN is 12Vdc (or anyway under 16Vdc), then it is not possible to use U34 unless it’s set to produce 5Vdc by JVLCD_12/5 (1-2)
- If DC_IN is over 16Vdc then it’s possible to use U34 for any setting of JVLCD_12/5.

U34 is the onboard DCDC to be used for the LCD backlight power of big panels (usually 8.4” and larger), which is typically 12Vdc. So you have also to know which LCD panel you are going to use.

Every LCD panel usually needs two voltages:
1. The voltage for its electronics, which is typically 3.3Vdc (up to 15” panels), or 5Vdc (17” to 21”), and even 12Vdc (32” and over)
2. The voltage for the backlight: 5V typically for small panels, 12Vdc for all other panels up to 21”, and 24Vdc for big panels (but in this case you will provide the backlight power directly, not through the C2 circuits, since the currents involved will be too high for the C2).

You will use the C2 FULL version for driving small and big panels, while the C2 Depopulated can be used only for small panels (typically: 7”).
5.3.2 POWER SUPPLY ROUTING FOR THE FULL-FEATURED C2

The FULL version of the C2 CPU board has all the 4 onboard DCDC subsystems (U31, U32, U33 and U34). This version of the C2 has been designed to support small and big LCD panels, since U33 and U34 can supply the necessary power for both panel’s electronics and panel’s backlight.

5.3.2.1 JVLCD_5/3 (C2 Full only)

Jumper JVLCD_5/3 allows choosing the voltage for pin 2 of the 6-pin header called JLVDS_PWR where you can select the supply voltage for the LVDS LCD connected to the C2.

- Set JVLCD_5/3 for 2-3 (default) if the LCD needs +3.3Vdc (e.g.: 8.4” or 10.4” or 12” or 15”)
- Set JVLCD_5/3 for 1-2 only if the LCD needs +5Vdc (e.g.: 17” or 19” or 21.5”)

![Fig. 10 Power Supply Routing Schematic of the C2 Full and default jumper settings](image)

![Fig. 11 JVLCD_5/3 (C2 Full only)](image)
5.3.2.2 J12V1 and J12V2 (C2 Full only)

Jumpers J12V1 and J12V2 are used to bypass U34 when the C2 is powered by 12Vdc and the voltage for the LCD backlight needs 12Vdc.

If the LCD backlight needs 5Vdc then you can use U34, provided the JVLCD_12/5 jumper is correctly set 1-2 (default).

- Set J12V1 and J12V2 both 2-3 if the C2 Full DC_IN is 12Vdc and backlight needs 12Vdc
- Set J12V1 and J12V2 both 1-2 if the C2 Full DC_IN is 12Vdc and the backlight needs 5Vdc → then set JVLCD_12/5 to 1-2
- Set J12V1 and J12V2 both 1-2 if the C2 Full is powered by 16Vdc or more, and the backlight needs 12Vdc → then set JVLCD_12/5 to 2-3
- Set J12V1 and J12V2 both 1-2 if the C2 Full is powered by 16Vdc or more, and the backlight needs 5Vdc → then set JVLCD_12/5 to 1-2

The table here below shows the possible combinations.

<table>
<thead>
<tr>
<th>J12V1</th>
<th>J12V2</th>
<th>JVLCD_12/5</th>
<th>DC_IN Power Supply</th>
<th>Effect</th>
</tr>
</thead>
<tbody>
<tr>
<td>2-3</td>
<td>2-3</td>
<td>Does not care, U34 bypassed</td>
<td>+12Vdc</td>
<td>V-Backlight 12Vdc</td>
</tr>
<tr>
<td>1-2</td>
<td>1-2</td>
<td>1-2</td>
<td>+12Vdc</td>
<td>V-Backlight 5Vdc</td>
</tr>
<tr>
<td>1-2</td>
<td>1-2</td>
<td>2-3</td>
<td>&gt; 16Vdc</td>
<td>V-Backlight 5Vdc</td>
</tr>
<tr>
<td>1-2</td>
<td>2-3</td>
<td>&gt; 16Vdc</td>
<td></td>
<td>V-Backlight 12Vdc</td>
</tr>
</tbody>
</table>
5.3.2.3 **JLVDS_PWR (C2 Full only)**

This is a 6-pin header which allows selecting the correct voltage for the LVDS LCD electronic. You can select the voltage to be +3.3Vdc, +5Vdc and +12Vdc. Refer to the LCD’s datasheet.

![Image of JLVDS_PWR](image)

**Fig. 14 JLVDS_PWR (C2 Full only)**

The connection of **JLVDS_PWR** for the **C2 Full version** is sensitive to the settings of jumpers **JVLCD_5/3**, **J12V1**, **J12V2** and **JVLCD_12/5**. The table here below shows the possible settings.

<table>
<thead>
<tr>
<th>JLVDS_PWR</th>
<th>DC_IN Power Supply</th>
<th>J12V1</th>
<th>J12V2</th>
<th>JVLCD_12/5</th>
<th>JVLCD_5/3</th>
<th>Resulting LVDS LCD Power available from LVDS24 conn.</th>
</tr>
</thead>
<tbody>
<tr>
<td>3-4</td>
<td>+12Vdc or higher</td>
<td>Does not care</td>
<td>Does not care</td>
<td>Does not care</td>
<td>Does not care</td>
<td>3.3Vdc from U32 (use with small 3.3V LCD only)</td>
</tr>
<tr>
<td></td>
<td>(default)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2-4</td>
<td>+12Vdc or higher</td>
<td>Does not care</td>
<td>Does not care</td>
<td>Does not care</td>
<td>2-3</td>
<td>3.3Vdc from U33 (use with bigger 3.3V LCD)</td>
</tr>
<tr>
<td></td>
<td>(default)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2-4</td>
<td>+12Vdc or higher</td>
<td>Does not care</td>
<td>Does not care</td>
<td>Does not care</td>
<td>1-2</td>
<td>5Vdc from U33 (use with bigger 5V LCD)</td>
</tr>
<tr>
<td></td>
<td>(default)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>4-6</td>
<td>+12Vdc</td>
<td>2-3</td>
<td>2-3</td>
<td>Does not care since U34 is bypassed</td>
<td>Does not care</td>
<td>12Vdc same as DC_IN (use with big LCD like 32&quot;) Make Sure 12Vdc DC_IN has enough current available</td>
</tr>
<tr>
<td>4-6</td>
<td>&gt; 16Vdc</td>
<td>1-2</td>
<td>1-2</td>
<td>1-2 (default)</td>
<td>Does not care</td>
<td>5Vdc from U34 (use with bigger 5V LCD)</td>
</tr>
<tr>
<td>4-6</td>
<td>&gt; 16Vdc</td>
<td>1-2</td>
<td>1-2</td>
<td>1-2 (default)</td>
<td>5Vdc from U34 (use with bigger 5V LCD)</td>
<td></td>
</tr>
<tr>
<td>4-6</td>
<td>&gt; 16Vdc</td>
<td>1-2</td>
<td>1-2</td>
<td>2-3</td>
<td>Does not care</td>
<td>12Vdc from U34 (use with big LCD like 32&quot;) Make Sure DC_IN has enough current</td>
</tr>
</tbody>
</table>

**Fig. 15 JLVDS_PWR jumper pin assignment and the 3 possible settings**

![Diagram of JLVDS_PWR](image)

**Fig. 16 Combinations allowed for Jumpers for LCD power (C2 Full only)**
5.3.2.4 BACKLIGHT SELECTION (C2 Full only)
The last step is the choice of the supply for the LCD’s backlight. The involved jumpers are JINV and JLCD7_P3.

The first simply selects between +5Vdc and the voltage which exits from J12V2: this voltage is then forwarded to the INV connector, where you will connect the LED driver or the CCFL inverter.

The second jumper does the same selection for the onboard LED driver which can be used for the LED backlight of small panels (like 7”). Wrong setting of this jumper can create board’s damage since its setting strictly depends on the setting of J12V1, J12V2 and JVLCD_12/5.

5.3.2.5 JINV (C2 Full only)
This jumper will bring the backlight power to pins 1 and 2 of the INV connector. The LCD’s LED Driver or CCFL Inverter will be connected to this INV connector. Table here below shows the allowed settings, since JINV strictly depends on the settings of J12V1, J12V2 and JVLCD_12/5.

<table>
<thead>
<tr>
<th>JINV</th>
<th>DC_IN Power Supply</th>
<th>J12V1</th>
<th>J12V2</th>
<th>JVLCD_12/5</th>
<th>Available Backlight Power</th>
</tr>
</thead>
<tbody>
<tr>
<td>1-2</td>
<td>Does not care</td>
<td>Does not care</td>
<td>Does not care</td>
<td></td>
<td>5Vdc from U31 (use with small LCD choice #1)</td>
</tr>
<tr>
<td>2-3</td>
<td>+12Vdc</td>
<td>2-3</td>
<td></td>
<td></td>
<td>12Vdc from DC_IN (use with bigger LCD)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Make Sure 12Vdc DC_IN has enough current</td>
</tr>
<tr>
<td>2-3</td>
<td>+12Vdc</td>
<td>1-2</td>
<td>1-2</td>
<td></td>
<td>5Vdc from U34 (use with small LCD choice #2)</td>
</tr>
<tr>
<td>2-3</td>
<td>&gt; 16Vdc</td>
<td>1-2</td>
<td>1-2</td>
<td></td>
<td>5Vdc from U34 (use with small LCD choice #2)</td>
</tr>
<tr>
<td>2-3</td>
<td>&gt; 16Vdc</td>
<td>1-2</td>
<td>1-2</td>
<td>2-3</td>
<td>12Vdc from U34 (use with bigger LCD)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Make Sure DC_IN has enough current</td>
</tr>
</tbody>
</table>

Fig. 17 JINV (C2 Full only)

Fig. 18 Combinations allowed for JINV jumper (C2 Full only)
5.3.2.6 JLCD7_P3 (C2 Full only)

This jumper’s name reminds its usage is for 7” LCD panels only. Its setting selects the voltage for the onboard LED driver (U50) which is used to power the LED backlight of the 7” panels which don’t have onboard LED driver.

The onboard LED driver of the C2 can only run from +5Vdc, otherwise U50 will burn. So it’s mandatory that the JLCD7_P3 setting never feeds 12Vdc (or higher voltage) to U50.

---

### Possible combinations for JLCD7_P3 jumper (C2 Full only)

<table>
<thead>
<tr>
<th>JLCD7_P3</th>
<th>DC_IN Power Supply</th>
<th>J12V1</th>
<th>J12V2</th>
<th>JVLC_12/5</th>
<th>Available Backlight Power</th>
</tr>
</thead>
<tbody>
<tr>
<td>2-3</td>
<td>5Vdc from U31</td>
<td></td>
<td></td>
<td></td>
<td>(use with small LCD choice #1)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>NOT ALLOWED</td>
</tr>
</tbody>
</table>

---

**Fig. 19 JLCD7_P3 (C2 Full only)**

**Fig. 20 Onboard LED Driver (for 7” small LCD panels)**

**Fig. 21 Possible combinations for JLCD7_P3 jumper (C2 Full only)**
5.3.2.7 JLCD7_P1 and JLCD7_P2 (C2 Full only)
These jumpers simply choose which TTL 7” LCD panel can be connected to the C2 (Full).

The setting of these jumpers is not affected by the setting of any other jumpers described before. There are only two allowed settings:

<table>
<thead>
<tr>
<th>JLCD7_P1 and JLCD7_P2</th>
<th>Selected TTL 7” LCD Panel</th>
</tr>
</thead>
<tbody>
<tr>
<td>1-2 Both (default)</td>
<td>LCD with onboard LED driver which needs 5Vdc</td>
</tr>
<tr>
<td></td>
<td>(like Data Image TTL 7” LCD)</td>
</tr>
<tr>
<td>2-3 Both</td>
<td>LCD without onboard LED driver</td>
</tr>
<tr>
<td></td>
<td>(like Chimei TTL 7” LCD)</td>
</tr>
</tbody>
</table>

Usually, 7” TTL LCD panels which don’t have onboard LED driver are the cheapest ones and often they have bonded 4W resistive touch.
5.3.3 POWER SUPPLY ROUTING FOR DEPOPULATED C2

The DEPOPULATED version of the C2 CPU board has only 2 onboard DCDC subsystems (U31 and U32). This version of the C2 has been designed to support small LCD panels, typically just only 7” TTL panels (or also 7” LVDS), which power can be supplied by U31 and U32 with no problem of overload.

U33 and U34, and also J12V1, J12V2, JVLCD_12/5, JVLCD_5/3 are not stuffed.

Notice that JLCD7_P3 is 2-3 by default, but if removed or set 1-2 then U50 will not be driven. This can save onboard power and minimize emissions if you don’t use the LED_BL connector.

JINV must be 1-2 and the only backlight power available from INV connector is +5Vdc.

Basically, the Depopulated C2 has been manufactured for small systems with 7” panels only.
5.3.3.1 JLVDS_PWR (DEPOPULATED C2 only)
This is a 6-pin header which allows selecting the correct voltage for the LVDS LCD electronic. You can only select +3.3Vdc. The default 2-3 setting is already what you need. It’s only valid for small LVDS panels. The TTL interface is not affected by this jumper setting.

![Fig. 25 JLVDS_PWR (Depopulated C2 only)](image)

5.3.3.2 BACKLIGHT SELECTION (DEPOPULATED C2)
The choice of the supply for the LCD’s backlight still involves jumpers JINV and JLCD7_P3. The first simply selects the +5Vdc and forwards to the INV connector, where you will connect the LED driver or the CCFL inverter of the 7” panel.

The second jumper does the same selection for the onboard LED driver U50 which can be used for the LED backlight of 7” panels which don’t have any LED driver onboard. The unique allowed setting is 1-2 (default), unless you don’t want to power up U50. Next chapters will detail the settings.

![Fig. 26 JLVDS_PWR jumper pin assignment and the only setting (C2 Depopulated)](image)
5.3.3.3 JINV
This jumper will bring the backlight power to pins 1 and 2 of the INV connector. The LCD’s LED Driver or CCFL Inverter will be connected to this INV connector. For 7” LCD panels, the INV connector is used mainly to supply the +5Vdc for LVDS version of the 7” LCD panels.
In fact, many 7” LCD panels which have onboard LED driver are TTL, and the onboard driver gets the +5V from the same 40 pin cable of the TTL signals.
If the 7” LCD is LVDS, the main cable from the LVDS connector of the C2 cannot give both voltages (3.3Vdc and 5Vdc) so you have to get the backlight voltage from the INV connector. And here pins 1 and 2 get the +5Vdc selected by JINV (set for 1-2).

Fig. 27 JINV (Depopulated C2)

<table>
<thead>
<tr>
<th>JINV</th>
<th>DC_IN Power Supply</th>
<th>J12V1</th>
<th>J12V2</th>
<th>JVLCD_12/5</th>
<th>Available Backlight Power to INV connector</th>
</tr>
</thead>
<tbody>
<tr>
<td>1-2</td>
<td>Does not care</td>
<td>Does not care</td>
<td>Does not care</td>
<td>Does not care</td>
<td>5Vdc from U31 (use with small LCD)</td>
</tr>
<tr>
<td>(default)</td>
<td>Does not care</td>
<td>Does not care</td>
<td>Does not care</td>
<td>Does not care</td>
<td>No power to INV connector</td>
</tr>
</tbody>
</table>

Fig. 28 Unique combination allowed for JINV jumper (Depopulated C2)
5.3.3.4 JLCD7_P3

This jumper’s name reminds its usage is for 7” LCD panels only. Its setting selects the voltage for the onboard LED driver (U50) which is used to power the LED backlight of the 7” LCD panels which don’t have onboard LED driver.

**JLCD7_P3** setting can be only 2-3. If JLCD7_P3 is set 1-2 in the Depopulated C2, the onboard LED driver U50 will not be active.

The onboard LED driver of the C2 can only run from +5Vdc. The JLCD7_P3 setting can be only 2-3. If JLCD7_P3 is set 1-2 in the Depopulated C2, the onboard LED driver U50 will not be active.

<table>
<thead>
<tr>
<th>JLCD7_P3</th>
<th>Available Backlight Power</th>
</tr>
</thead>
<tbody>
<tr>
<td>2-3</td>
<td>5Vdc from U31 (use with small LCD choice #1)</td>
</tr>
<tr>
<td>OPEN</td>
<td>Onboard LED Driver (U50) is disabled (remove cap from Jumper JLCD7_P3 if using LVDS 7” LCD panel)</td>
</tr>
</tbody>
</table>

**Fig. 29 JLCD7_P3 (Depopulated C2)**

**Fig. 30 Onboard LED Driver (for 7” small LCD panels)**

**Fig. 31 Combinations permitted for JLCD7_P3 jumper (Depopulated C2)**
5.3.3.5  **JLCD7_P1 and JLCD7_P2**

These jumpers simply choose which TTL 7” LCD panel can be connected to the C2 (Depopulated).

![Diagram of JLCD7_P1 and JLCD7_P2](image)

**Fig. 32  JLCD7_P1 and JLCD7_P2 (C2 Full)**

The setting of these jumpers is not affected by the setting of any other jumpers described before. There are only two allowed settings:

<table>
<thead>
<tr>
<th>JLCD7_P1 and JLCD7_P2</th>
<th>Selected TTL 7” LCD Panel</th>
</tr>
</thead>
<tbody>
<tr>
<td>1-2</td>
<td>LCD with onboard LED driver which needs 5Vdc (like Data Image TTL 7” LCD)</td>
</tr>
<tr>
<td>Both (default)</td>
<td></td>
</tr>
<tr>
<td>2-3</td>
<td>LCD without onboard LED driver (like ChiMei TTL 7” LCD)</td>
</tr>
<tr>
<td>Both</td>
<td></td>
</tr>
</tbody>
</table>

**Fig. 33  Combinations for JLCD7_P1 and JLCD7_P2 jumpers (Depopulated C2)**

Usually, 7” TTL LCD panels which don’t have onboard LED driver are the cheapest ones and often they have bonded 4W resistive touch.
5.4 OTHER JUMPERS (Full & Depopulated C2)

There are other jumpers on the C2, which will be described here below. The jumper setting is valid for both the FULL version and the DEPOPULATED version. The images here below show the Default Setting of each Jumper.

5.4.1 JPWM

Default 1-2

⇒ GPIO_1 (PIN B7 uP) controls the Backlight of TTL LCD

If JPWM is set 1-2 then GPIO_1 (pin B7 of iMX53) can control the brightness of the TTL 7” panel (both LCD models: with onboard and without onboard LED driver).

If JPWM is set 2-3 then GPIO_1 (pin B7 of iMX53) will be connected to the INV connector (pin 4).

If JPWM is OPEN, brightness control will be always pulled up to Vcc, hence set to maximum (see also the requirements of the CCFL Inverter or LED-Driver, since some CCFL inverters give max brightness when this signal is close to GND and not to Vcc).

5.4.2 JCOM2

Default 1-2 and 3-4

Set COM2 for RS422

This header allows selecting the behavior of the COM2 serial port. See the relevant chapter.
5.4.3 **JP_485_REC_EN**  
Default 2-3  
(RECEIVER ALWAYS ENABLED)

5.4.4 **JP_485_TERMINATION**  
Default 1-2  
(RS485 LINE TERMINATED)

5.4.5 **JP_485_RTS_CHOICE**  
Default 1-2  
(INVERTED RTS TO CHIP)

These three jumpers set the behavior of the COM1 serial port interface. See the relevant chapter.

5.4.6 **JCAN_RS**  
Default 1-2  
CAN Slew Rate limited to 500kb/s

5.4.7 **J120R_CAN**  
Default 1-2  
CAN Line Termination Enabled

These two jumpers set the behavior of the CANbus interface. See the relevant chapter.
5.4.8 JBAT_EN
Default 2-3 (battery off)

This jumper connects/disconnects the onboard 3V coin battery.

Image shows the in-usage position. Restore to parking position (2-3) if the board is in the shelf or not used for a long period.
6 CONNECTORS

6.1 CONNECTOR TOPOLOGY of the C2 CPU Board (TOP)

Please always refer to the board TOP topology as from below drawing.

Fig. 34 Topology of the Board (TOP). Lower Side is the Connector Area.
6.2 TOPOLOGY of the C2 CPU Board (BOTTOM)

Please always refer to the board BOTTOM topology as from below drawing. Since we’re looking at the board from bottom side, LEFT and RIGHT sides are reversed.

![Board Topology Diagram]

Fig. 35 Topology of the Board (BOTTOM). Lower Side is the Connector Area.

6.2.1 HOW TO RECOGNIZE PIN 1 (CONNECTORS & JUMPERS)

To recognize Pin 1 of Connectors & Jumpers, the rules are the following:

5) Pin 1 of Jumpers is evidenced by a **bold square** around
6) Pin 1 of Connectors is evidenced by a **bold marking** at side of Pin 1
7) Underneath (BOTTOM Side) Pin 1 has always a **square pad** (others have round pads)
8) In most cases, where there is room, pins are numbered.

![Pin 1 Recognition Examples]

Fig. 36 Examples of Silk-Screen figures to recognize Pin 1
6.3 DC_IN  
POWER SUPPLY CONNECTOR

The DC_IN connector is placed near the Lower Left corner.

Pin assignment is from right to left (looking from front):

1 = +12Vdc~36Vdc
2 = GND
3 = Frame Ground

This is the schematic portion. Notice the soldered fuse (Fuse 1) near the connector.

DCIN: 12Vdc or 19V~30V (Typical 24V)
PHOENIX COMBICON 1731688 MC 1.5/3-G-3,5-RN or equivalent

Be careful to avoid any DC_IN polarity inversion.
R82 normally keeps Case_GND and GND connected together.
6.4 COM2  DSUB9M SERIAL PORT (RS232/422/485) CONNECTOR  
This is placed at right of DC_IN connector, lower left edge of the board.

![Diagram of COM2 Connector](image)

*Fig. 40 The COM2 Connector. Notice the JCOM2 pin-header*

Pin assignment is defined here below:

![Diagram of COM2 Pin Assignment](image)

*Fig. 41 Signals of the COM2 Connector*

Pin function depends on jumper setting of the U10 (SP339E) interface chipset. This one gets the rough signals directly from the ARM iMX53x processor (UART3 port).

U10 allows choosing between RS232 or RS485 or RS422 according to JCOM2 pin-header.

See next page for Jumper settings for: SLEW, TERM, MODE0 and MODE1.
6.4.1 COM2 JUMPER SETTINGS: the JCOM2 pin header

These jumpers are just above the DSUB9M connectors:

![Image of JCOM2 pin header]

*Fig. 42 The “JCOM2” pin-header for COM2 (notice default settings)*

6.4.1.1 SETTING JUMPERS TERMINATION & SLEW-RATE:

- TERM JUMPER (7+8)
  - CLOSED ➔ SETS TERMINATION 120 OHM FOR RS485 OR RS422 ONLY
  - OPEN ➔ NO TERMINATION

- SLEW JUMPER (5+6)
  - CLOSED ➔ ENABLES 250kbps SLEW LIMITING
  - OPEN ➔ disables slew limiting

6.4.1.2 SETTING JUMPERS FOR RS232 or RS485 or RS422 COM2 MODE

Here is the table for the correct jumper setting of JCOM2 header. The jumpers have 2.0mm pitch.

<table>
<thead>
<tr>
<th>Mode</th>
<th>JUMPER MODE-1 Pins 1-2</th>
<th>JUMPER MODE-0 Pins 3-4</th>
<th>SELECTED MODE</th>
<th>RESULTING COM2 FUNCTION ASSIGNMENT</th>
</tr>
</thead>
<tbody>
<tr>
<td>-</td>
<td>OPEN OPEN</td>
<td>X</td>
<td>NOT ALLOWED</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>OPEN CLOSED</td>
<td>RS232</td>
<td>1=DCD, 2=RX, 3=TX, 4=DTR, 5=GND, 6=DSR, 7=RTS, 8=CTS, 9=RI</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>CLOSED OPEN</td>
<td>RS-485 HALF DUPLEX</td>
<td>1=DATA-, 2=DATA+, 3=GND</td>
<td></td>
</tr>
<tr>
<td>3a</td>
<td>CLOSED CLOSED</td>
<td>RS-422 FULL DUPLEX DEFAULT</td>
<td>1=TX-, 2=TX+, 3=RX+, 4=RX-, 5=GND</td>
<td></td>
</tr>
<tr>
<td>3b</td>
<td>CLOSED CLOSED</td>
<td>RS-485 With TX read-back DEFAULT</td>
<td>1=TX-, 2=TX+, 3=RX+, 4=RX-, 5=GND</td>
<td>This setting is used to have the TX'ed data read back at the same time you transmit. Connect pins 1 + 4 and 2 + 3 of COM2 DB9 connector. After this, TX-/RX- become DATA- and TX+/RX+ become DATA+</td>
</tr>
</tbody>
</table>

*Fig. 43 How to set JCOM2 for different COM2 operation*

Please notice that you can have 4 different settings for COM2. Next chapter will explain in detail.
6.4.2 Explanation of RS485 Settings

Normally the COM2 port settings allow 3 different modes of operation:

- **RS232** - **Full duplex**, single-ended signals, RX, TX, RTS and CTS for full handshake. Suitable for short range communications since it can pick up a lot of noise. It’s **Mode 1** from above table.
- **RS422** - **Full-duplex** as the RS232, only TX and RX. Signals are differential (TX- and TX+, RX- and RX+) to allow a very high noise rejection. Allows communication over long distance. It’s **Mode 3a** from above table.
- **RS485** - **Half Duplex** only. When you transmit you cannot receive. Two wires only: Data+ and Data-. Differential signals to allow a very high noise rejection. Allows communication over long distance. It’s **Mode 2** from above table.

The major problem of an RS485 communication is that when the transmit driver is on, the receiver is off since they are driven by the same control signal (RTS): direct for TX and inverted for RX.

![Fig. 44 Typical RS485 Driver/Receiver](image)

This is not so good because you cannot understand when the TX flux has ended and you can exchange the direction of the driver/receiver (changing the level of RTS).

**When you set the JCOM2 pin header for Mode 2, you get exactly the circuitry shown above.**

In some cases this is enough, but in many others you need to understand quickly when it’s time to change the direction. Then, you have to use the circuit below:

![Fig. 45 RS422 modified for RS485 with TX data instant read-back](image)

This is **Mode 3b** and the RX receiver is *always enabled* while you enable the TX driver only when you need to transmit. Since the RX receiver is always enabled, you will read your TX’ed data as soon as it exits from the driver. **This mode needs an external wiring (red wires) to the COM2 DB9 connector: connect pins 1+4 and 2+3 and you get the RS485 DATA+ and DATA-.**
6.5 COM1 ISOLATED SERIAL PORT (RS485) CONNECTOR

This is placed between the DSUB9M connector and the USB connector, lower left edge of the board. There are 3 jumpers which set some features of the COM port.

![Fig. 46 The COM1 Connector (Isolated RS485 Serial Port)](image)

6.5.1 COM1 Pin Assignment

The COM1 pin assignment for RS485 (isolated) is evidenced here below.

![Fig. 47 COM1 Connector pin assignment](image)

The COM1 port is an isolated RS485 by default. Eventually it can be also used as RS422 (isolated) but it needs a small h/w modification which can be only made by CJB.

Pin-Header **JP_485_Termination** (circled in RED in upper drawing) allows setting the line termination for the RS485. Setting 1-2 enables the RS-485 termination.

**Notice:** this RS485 interface is already a TX-read-back interface (like mode 3b for COM2). You don’t have to do nothing to set this behaviour which is already by default for COM1.

Next paragraph details the Jumper settings for COM1.
6.5.2 COM1 Settings
There are three jumpers to set COM1 functionality:

The only jumper you are allowed to change is the **Termination Jumper**. Never change the other two jumpers nearby.

### 6.5.2.1 Termination Jumper Setting for COM1
The settings are the following:

- **1+2** **Termination enabled** To be set when the C2 is at one end of the daisy-chain of RS485 boards connected each other

- **2+3** **Termination disabled** To be set when the C2 is in a middle position of the daisy-chain of RS485 boards connected each other
6.6 USB_A, USB_B

USB TYPE_A HOST CONNECTORS

They are placed between the COM1 and the LAN1 connectors, lower centre edge of the board.

Fig. 50 The USB_A and USB_B Type_A USB ports

These are common Type_A host connectors. Inside the CPU board circuitry, these are USB Channels 1 and 2.

Fig. 51 Schematic of the Connector used for USB_A and USB_B
6.7 USB_D, USB_E

USB AUX HOST PIN HEADER CONNECTORS

They are placed near the lower right corner of the board.

These are 4-pin headers wired as below.

Fig. 52 The USB_D and USB_E Pin-headers for onboard additional USB ports

PIN ASSIGNMENT:

1. VCC (red wire)
2. DATA- (white wire)
3. DATA+ (green wire)
4. GND (black wire)

Fig. 53 USB_D and USB_E wiring
6.8 LAN1, LAN2  FAST ETHERNET #1 & #2 CONNECTORS, RJ45
These are two RJ45 connector for onboard Ethernet channel #0 (left) and #1 (right). They are placed in the lower edge of the CPU board, side-to-side each other.
Notice: ETH1 (right connector) is stuffed only in the fully populated version of the board.

The signals of each of these ports follow the standard assignment, as you can see here below.

The MAC address for each port has been programmed in factory; the value is the label stuck onto each RJ45 connector block.
6.9 CAN, CAN-V  CANBUS interface CONNECTORS
These are placed at right of rightmost Ethernet connector (ETH1), lower right edge of the board. The two connectors have the same pinout, and are in parallel, to allow an easy connection when the C2 is eventually placed in the middle of the daisy-chain of CANbus modules.

![Fig. 56 CANbus twin connectors](image)

The connectors have the following pin assignment:

1. GROUND_CAN (NOT ISOLATED)
2. CAN_H
3. CAN_L
4. n.c.

![Fig. 57 Pin Assignment of CANbus connector](image)

There are two connectors because this makes easy the usage of the board amid a “daisy chain” of CANbus connections. In other words, when the C2 is used not as ending node, but in the mid of the fieldbus, you will have one cable connected from connector CAN (90° connector) to an I/O module and another cable connected from connector CAN-V (vertical) to another module.

IMPORTANT NOTICE: if you are using the C2 inside the fieldbus, make sure the termination resistor (J120R_CAN) is not enabled. See following chapter which details the settings of the CANbus interface.
6.9.1 CANbus Interface Settings

There are two jumpers near the 90° CAN connector. They allow for the Line Termination insertion, and for the bus speed limiting.

The schematic here below shows the circuitry of the CANbus interface. The Line Termination resistor must be inserted when the board is at one end of the daisy-chain connection between the CANbus modules. It can be set with Jumper J120R_CAN (the rightmost of the two jumpers): closing 1-2 sets the termination resistor.

The JCAN_RS pin header (placed nearby the connector) allows selection of CANbus speed limiting.

The JCAN_RS pin header (placed nearby the connector) allows selection of CANbus speed limiting.

![Fig. 58 CANbus Settings Jumpers](image)

![Fig. 59 Schematic of CANbus interface](image)

<table>
<thead>
<tr>
<th>JCAN_RS</th>
<th>J120R_CAN</th>
</tr>
</thead>
<tbody>
<tr>
<td>1-2</td>
<td>High Speed</td>
</tr>
<tr>
<td>2-3</td>
<td>Low Speed</td>
</tr>
<tr>
<td>1-2</td>
<td>Termination Inserted</td>
</tr>
<tr>
<td>2-3</td>
<td>No Termination</td>
</tr>
</tbody>
</table>

![Fig. 60 Jumper Setting for CANbus interface (default setting is displayed)](image)
6.10 VGA (VGA Pin Header CONNECTOR)

The VGA interface is made of a 10 (2x5) pin header, 2.0mm pitch, and it’s placed near the mid centre right side of the board.

![VGA Connector (Pin Header)](image1)

You can wire a short cable from this pin-header to a common female DSUB15F, to obtain the common VGA connector like any PC. Connections are the following, seen from the REAR SIDE (solder wire side) of the DSUB15F Female connector:

![Signals of the VGA Pin Header](image2)

<table>
<thead>
<tr>
<th>SIGNAL NAME</th>
<th>C2 VGA PIN Header</th>
<th>DSUB15F PIN</th>
</tr>
</thead>
<tbody>
<tr>
<td>RED</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>GREEN</td>
<td>3</td>
<td>2</td>
</tr>
<tr>
<td>BLUE</td>
<td>5</td>
<td>3</td>
</tr>
<tr>
<td>HORIZONTAL</td>
<td>7</td>
<td>13</td>
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<td>VERTICAL</td>
<td>9</td>
<td>14</td>
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<tr>
<td>GND</td>
<td>6,8,10</td>
<td>5,6,7,8,10</td>
</tr>
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<td>DATA VGA_I2C_SDA</td>
<td>2</td>
<td>12</td>
</tr>
<tr>
<td>CLOCK VGA_I2C_SCL</td>
<td>4</td>
<td>15</td>
</tr>
</tbody>
</table>

![VGA DSUB15F seen from rear side (wire solder side)](image3)
6.11 LVDS CONNECTOR

This is one 40 pin (2x20) header, and its location is near the left of the VGA connector pin header. The LVDS Port can support 2-Channels, 24-bits LCD panels with resolution up to 1920x1080 (1080p).

Since LCD panels may require different power supplies, you have to check the correct jumper settings for LVDS Power before connecting an LCD. The details of the LCD jumper settings are covered in next paragraphs. Ask CJB for pin assignment between the C2 LVDS connector and your panel. Since R213 + R214 are not stuffed and R226 + R227 are, pins 25 and 26 are two ground pins.

The power rail called +VLVDS is the power for the LCD electronics, and the voltage can be selected by the JLVDS_PWR pin header. Default setting is 3.3Vdc (3-4).

Each panel also needs power for the backlight. Details of the relevant connector (INV) are described in next paragraph.
6.12 INV (INVERTER / LED DRIVER POWER CONNECTOR)

This 6 pin 2.5mm pitch male header is the central of the three connectors on upper left edge of the board. Notice that the leftmost connector (“1W”) is optional and it’s never stuffed by factory. The INV connector is used to bring power to LCD’s inverter or LED backlight driver. Usually brings 12Vdc which is the most common voltage for powering Inverters or LED drivers.

The schematic here below details how the INV connector has been wired to the typical signals and power rails used for Inverters and for LED drivers.

A detailed discussion of the signals and power rails is in the following paragraph.
6.12.1 Analysis of the INV Connector’s signals

Looking at the schematic of the previous paragraph, you can recognize that:

1. **Power Selection: +12/+5**
   The Inverter/LED-driver power (for pins 1 and 2) can be selected between +5Vdc and +12Vdc by setting the jumper of JINV pin header.

2. **Backlight ON/OFF**
   Since usually either an Inverter or a LED-driver need a positive signal for Enable, the INV_EN signal to pin 3 is kept at positive (high) level by default. To shut off the lamps, the GPIO signal “LCD_BLT_EN” must be forced to low level.

3. **Dimming for CCFL Inverters**
   Usually CCFL Inverters have limited dimming capabilities: they usually need 0Vdc for max brightness, and 5Vdc (or 3.3Vdc) for min brightness, which usually is only 70% of the max brightness. In this case you can drive the GPIO signal “LVDS24_PWM” either low or high, to have the max or min brightness for the CCFL inverter.
   Notice that default is min brightness by the pull-up resistor R534.

4. **Dimming for LED Drivers**
   LED Drivers often have similar features (behave like the CCFL inverters), but nowadays the most diffused LED Driver models need a Dimming action managed by PWM. That means you will apply a fixed frequency square wave (1 kHz, for example) but with variable duty factor of the square wave:

   ![PWM control by variable duty factor](image)

   The figure above shows the solid 50% duty-factor square wave which will drive the backlight 50% of the brightness; the red square wave shows an example of ~85%duty factor, where the wave stays at high level for 85% of the cycle. This will drive the brightness to 85%. The green wave shows the opposite, i.e. one 15% duty factor only, for a 15% of the available brightness.
   If you drive the PWM input with permanently high signal, you get max brightness, like 100% duty factor; if you drive the PWM input with a permanently low signal, you shut off the backlight (0% brightness).
   **Important:** some LED-driver boards do not allow 0% duty factor. They always need a minimal duty factor (like 1% or 2%) otherwise faults can occur. Please get all the needed information for correct drive of your LED-driver board.

6.12.2 Pin Assignment for INV connector

This is the pin assignment of the INV connector:

1. +12Vdc (JINV 2-3) or +5Vdc (JINV 1-2) (fused) **Default is +5Vdc**
2. **Same as above pin 1**
3. Enable also called ON/OFF (High = ON) **Default is High level**
4. PWM (LED) or Brightness (CCFL) **Default is High level**
   a. *Usually High or 100% PWM sets max brightness to LED Driver boards*
   b. *Usually Low or GROUND sets max brightness to CCFL inverter*
5. GND
6. GND
6.13 AUDIO CONNECTOR

There is one pin-header, 10 (2x5) pins, 2.0mm pitch, for the Audio interface signals, almost mid centre of the board, just near the innermost mounting hole.

This connector has all the typical signals of a standard Audio Interface:

| LINE_OUT  | 1 = Line_Out_Left | 3,5 = GND | 7 = Line_Out_Right |
| LINE_IN   | 2 = Line_In_Left  | 4,6 = GND | 8 = Line_In_Right  |
| MIC_IN    | 10 = MIC_Input    | 9 = GND   |                    |

**Fig. 70 The Audio Connector**

**Fig. 71 Pin Assignment of the Audio Connector**

**Fig. 72 Circuitry of the Audio Connector; note the orientation and pin numbers!**

WARNING: *Never use the Line_OUT signals to drive a speaker or a headphone.* The signals exiting from the C2 are low power and need always to be amplified externally.

The **MIC_IN** should be connected to a common PC electret-condenser mike.
6.14 SPI1 CONNECTOR

The SPI1 connector is one 10-pin header near the USBD header connector, right side of the board. It has the signals which can be used for a high-speed SPI interface, including +3.3V and +5V power supplies (not protected, so be careful when using them to power external devices).

![SPI1 Connector](image)

**Fig. 73** SPI1 Connector; note the orientation and pin numbers!

From this header you will have the **MOSI** (Master Output to Slave Input), the **MISO** (Master Input from Slave Output), a **Serial Clock**, and a **Chip-Select** (ECSP11_SS1). All signals have a 5V level (since they are translated by U35). Common Ground is available on Pin 7.

![SPI1 Connector wiring and level translator U35](image)

**Fig. 74** SPI1 Connector wiring and level translator U35
6.15 UART_DEBUG PORT

To survey the boot up of the board, you must connect the “Debug” port to a PC, where a suitable “Console Simulator” program is running. For example: PUTTY or HyperTerminal or other similar programs.

Since modern PC’s do not have COM ports, it’s suggested to use an USB ⇔ COM (TTL1.8V) conversion cable, like the FTDI model TTL-232RG-VREG1V8-WE, which TTL signals commit the 1.8Vdc levels required by the C2 Debug Port. Such cable appears like the photo here below (where we have already wired the small white connector for the Debug Port).

The schematic of the Debug Port is here below:

When preparing the cable, wire one JST B6B-PH-K 6-pin female so that the TX wire of the conversion cable is connected to pin 6 (RX), the RX wire of the cable is connected to pin 4 (TX), and the Ground wire is connected to pin 3. The 1.8Vdc wire usually provided by the cable must not be connected.
6.16 USB-OTG CLIENT USB DEBUG CONNECTION

This connector is a 5pin header, 2.0mm pitch, available for debug Client USB port. You have to setup an adaptor cable to match your cable. If you want to plug directly to one Type_A port of your PC, it’s a good idea to provide a cable with such 2.0mm 5 pin female at C2 board side, and a male Type_A connector at the opposite side.

Pin assignment:

1. Vcc (usually red wire)
2. Data- (White wire)
3. Data+ (Green wire)
4. GND (Black wire)
5. Shield (shield braid) → or same GND if cable is short

6.16.1 OTG CABLE EXAMPLE:

Here below you can see a simple example of a cable which can support this connection. When wiring the cable, follow the wire colour matching.

Fig. 78 USB_OTG Connector

Fig. 79 USB_OTG Cable example
6.17 1W  1-WIRE PERIPHERAL CONNECTOR (OPTIONAL)

This connector is a 5pin header, 2.0mm pitch, available for 1-Wire (Dallas) peripherals. It’s upper left edge of the board, near Fuse5, near LCD Inverter (INV) connector.

![Fig. 80 Optional 1W Connector](image)

The 1-Wire interface can be used for simple peripherals like temperature sensors. It’s a Dallas proprietary bus. Peripherals are powered by +5Vdc with 0.1A fuse.

![Fig. 81 Optional 1W Connector](image)

Pin Assignment:

1. GROUND
2. GROUND
3. SIGNAL
4. +5Vdc
5. n.c.
6.18 RESET  EXTERNAL RESET CONNECTOR
This connector is a 2pin header, 2.0mm pitch, available for external reset. It’s near the upper side of the board, below the three white connectors. It’s paralleled with the SW3 pushbutton which can be used for triggering a manual reset to the C2 board.

![Fig. 82 RESET Connector and Manual Reset Pushbutton (SW3)](image1)

![Fig. 83 Schematic of the RESET Connector and SW3 Pushbutton](image2)

Shorting the two pins of the RESET connector makes a hardware cold-reset sent immediately to the board. The pin assignment is the following:

Pin 1 = GND       Pin 2 = Reset

6.19 SW3  MANUAL RESET PUSHBUTTON
Same effect is made just pushing the SW3 pushbutton.
6.20 SW4 - USER DEFINED INPUT #1 (ONLY FOR C2 Depopulated)

The depopulated version of the C2 has been prepared with a 2.0mm connector (box header), where for example a pushbutton can be connected for issuing external commands to the C2 CPU board.

Only SW4 has been upgraded with the box header for room issue on the C2. The signal is the USERDEF1 connected to PATA_DATA14 (pin P6) of the IMX53. Pin 1 (GND) is the pin nearest to the assembly hole (see the photograph here below).
6.21 GPIO TTL I/O CONNECTOR

This is a 44pin 2.0mm pitch shrouded male header with 25 TTL I/O signals coming from the iMX53 native GPIO resources. The connector is on upper edge, right side of the board, between the two mounting holes nearby.

Pin assignment of the GPIO Connector is the following:

- Pins 1, 2, 41, 42 = +3.3Vdc
- Pins 3, 4, 15, 16, 27, 28, 39, 40, 43, 44 = GND
- Pins 5 → 12 = GPIOA_P00 → GPIOA_P07
- Pins 13, 14 = GPIOA_P10, GPIOA_P11
- Pins 17 → 22 = GPIOA_P12 → GPIOA_P17
- Pins 23 → 26 = GPIOA_P20 → GPIOA_P23
- Pins 29 → 32 = GPIOA_P24 → GPIOA_P27

The GPIO signals provide 3.3Vdc levels, and need to be conditioned externally (unless they are connected to TTL devices). All GPIO’s have a 10K pull-up resistor to +3.3Vdc.
6.21.1 TTL GPIO WIRING

The following page shows in detail the GPIO mapping from the iMX53.

Fig. 87 The GPIO Connector: wiring and signals involved
### 6.21.2 GPIO Mapping from iMX53

The table which follows shows the mapping of the GPIO resources which come from the iMX53 ARM processor and are brought to the GPIO 44 pin Connector of the C2. Please refer to the iMX53 Programming Manual for the usage of these GPIO signals.

<table>
<thead>
<tr>
<th>Pin #</th>
<th>Wire Description</th>
<th>CPU PAD</th>
<th>ALT</th>
<th>Bit</th>
<th>Port</th>
<th>Position</th>
<th>Address</th>
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</table>

*Fig. 88 The GPIO Connector: mapping of the signals involved*
6.22 3G_MALE: PIGGYBACK 3G EXPANSION CONNECTOR (OPTIONAL)

This is an optional 30pin 2.0mm pitch male header which has the signals needed for the piggyback 3G module, designed to host one Mini-PCI-express (MPCIe) mini-card holder. The piggyback plugs into this socket and is secured in three points with studs.

The piggy-back board has both the MPCIe socket (USB signals only) and the SIM card socket. The SMA connector is for the 3G antenna.

The drawing here below shows the piggyback board layout.

![Fig. 89 Layout of the 3G piggyback board](image)

This feature is optional, and even if the 3G_MALE header is stuffed, by default the USBE connection is not brought to this connector, but used, normally, for the USB connector. Here below is the schematic of this male header.

![Fig. 90 Schematic of the 3G piggy board interface connector](image)

Normally commercial MPCIe 3G modules require 2A (or more) at 3.3Vdc. That’s why to use this board you need the fully populated C2 version, and set the Power Selection for U33 to 3.3V, so you get enough power from the onboard DCDC (U33). This may create conflicts with LCD power requirements, so be careful. See also the Chapter regarding the Power Routing of the C2.
6.23 LCD7 (BOTTOM SIDE) 7” TTL PANEL FLAT CABLE
This is a snap-in 40 pin FPC (flex PCB Cable) connector for a 18-bit RGB TTL 7” 800x480 LCD panel. It’s placed at bottom side of PCBA, almost in centre of the board. Its position has been designed so that the FPC Cable can be easily connected to one 7” panel, and stay aligned with the LCD’s FPC connector.

![Fig. 91 The LCD7 Connector: designed for instant connection of a 7” LCD](image)

The connector has a hinged brown clip which can be raised (gently) with a fingernail. Then the FPC cable must be carefully slid in the connector with the brown clip kept opened. **The blue side of the FPC cable must stay on top (visible).** Then the brown clip has to be pushed downward (gently) to keep the FPC cable firmly in place.

The result will look like the image here below (where the LCD panel has been stuffed into a metal frame for ease of assembly in the final customer’s configuration).

![Fig. 92 The 40pin FPC cable connect the C2 to the TTL 7” LCD](image)

As you can see, the connection is straightforward, and when the C2 is rotated over the LCD (to make a “sandwich”) the FPC cable has plenty of ease to bend without any risk of damage, since both TTL connectors (LCD and C2) stay on the same axis.
6.23.1 FLEXIBLE 7” LCD INTERFACE

Two different models of 7” panels can be connected. CJB will suggest the correct models and also provide to you. Basically, you can connect either 7” panel with onboard LED driver, or 7” panels which need an external LED driver. Usually these latter panels are cheaper and are usually bonded with 4W resistive touch-screen.

The C2 can support both the supply for the LED backlight, and the 4W resistive touch interface.

6.23.1.1 Interface for 7” LCD with onboard LED driver

For this models the wiring is the following:

<table>
<thead>
<tr>
<th>Pin No.</th>
<th>SYMBOL</th>
<th>DESCRIPTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Vss</td>
<td>Power Ground</td>
</tr>
<tr>
<td>2</td>
<td>Vss</td>
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</tr>
<tr>
<td>3</td>
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<td>Brightness control for LED B/L</td>
</tr>
<tr>
<td>4</td>
<td>VDD</td>
<td>Power Supply for LED Driver circuit</td>
</tr>
<tr>
<td>5</td>
<td>VDD</td>
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</tr>
<tr>
<td>6</td>
<td>VDD</td>
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</tr>
<tr>
<td>7</td>
<td>Vcc</td>
<td>Power Supply for Digital Circuit</td>
</tr>
<tr>
<td>8</td>
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<td>Power Supply for Digital Circuit</td>
</tr>
<tr>
<td>9</td>
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<td>Data Enable</td>
</tr>
<tr>
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</tr>
<tr>
<td>11</td>
<td>Vss</td>
<td>Power Ground</td>
</tr>
<tr>
<td>12</td>
<td>Vss</td>
<td>Power Ground</td>
</tr>
<tr>
<td>13</td>
<td>B5</td>
<td>Blue Data 5 (MSB)</td>
</tr>
<tr>
<td>14</td>
<td>B4</td>
<td>Blue Data 4</td>
</tr>
<tr>
<td>15</td>
<td>B3</td>
<td>Blue Data 3</td>
</tr>
<tr>
<td>16</td>
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<td>Power Ground</td>
</tr>
<tr>
<td>17</td>
<td>B2</td>
<td>Blue Data 2</td>
</tr>
<tr>
<td>18</td>
<td>B1</td>
<td>Blue Data 1</td>
</tr>
<tr>
<td>19</td>
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</tr>
<tr>
<td>20</td>
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<td>Power Ground</td>
</tr>
<tr>
<td>21</td>
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</tr>
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<td>22</td>
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</tr>
<tr>
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<td>G3</td>
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</tr>
<tr>
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</tr>
<tr>
<td>25</td>
<td>G2</td>
<td>Green Data 2</td>
</tr>
<tr>
<td>26</td>
<td>G1</td>
<td>Green Data 1</td>
</tr>
<tr>
<td>27</td>
<td>G0</td>
<td>Green Data 0 (LSB)</td>
</tr>
<tr>
<td>28</td>
<td>Vss</td>
<td>Power Ground</td>
</tr>
<tr>
<td>29</td>
<td>R5</td>
<td>Red Data 5 (MSB)</td>
</tr>
<tr>
<td>30</td>
<td>R4</td>
<td>Red Data 4</td>
</tr>
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<td>31</td>
<td>R3</td>
<td>Red Data 3</td>
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<tr>
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<td>Power Ground</td>
</tr>
<tr>
<td>33</td>
<td>R2</td>
<td>Red Data 2</td>
</tr>
<tr>
<td>34</td>
<td>R1</td>
<td>Red Data 1</td>
</tr>
<tr>
<td>35</td>
<td>R0</td>
<td>Red Data 0 (LSB)</td>
</tr>
<tr>
<td>36</td>
<td>Vss</td>
<td>Power Ground</td>
</tr>
<tr>
<td>37</td>
<td>Vss</td>
<td>Power Ground</td>
</tr>
<tr>
<td>38</td>
<td>DCLK</td>
<td>Clock Signals : Latch Data at the Falling Edge</td>
</tr>
<tr>
<td>39</td>
<td>Vss</td>
<td>Power Ground</td>
</tr>
<tr>
<td>40</td>
<td>Vss</td>
<td>Power Ground</td>
</tr>
</tbody>
</table>

Notice that Pins 4, 5 and 6 are the supply for the LED backlight (usually +5Vdc) while Pin 3 is the dimming control: PWM, if fixed at high level (3.3Vdc) the brightness is max., if fixed at low level (GND) the backlight is off. Vcc is the LCD power (3.3Vdc).
6.23.1.2 Interface for 7” LCD with external LED driver

Most cheap 7” TTL panels with onboard bonded resistive touch don’t have any onboard LED backlight driver, so the power for the backlight must be provided from outside.

The C2 can do that (see following chapters), but care must be taken because for such panels the 40 pin TTL interface is different, as you can see from the table here below.

<table>
<thead>
<tr>
<th>Pin No</th>
<th>Symbol</th>
<th>Description</th>
<th>Remark</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>GND</td>
<td>Power Ground</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>GND</td>
<td>Power Ground</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>NC</td>
<td>Not Connect</td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>B5</td>
<td>Power Supply for Digital Circuit</td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>B5</td>
<td>Power Supply for Digital Circuit</td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>B5</td>
<td>Power Supply for Digital Circuit</td>
<td></td>
</tr>
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<td>7</td>
<td>B5</td>
<td>Power Supply for Digital Circuit</td>
<td></td>
</tr>
<tr>
<td>8</td>
<td>NC</td>
<td>Not Connect</td>
<td></td>
</tr>
<tr>
<td>9</td>
<td>DE</td>
<td>Data Enable</td>
<td></td>
</tr>
<tr>
<td>10</td>
<td>GND</td>
<td>Power Ground</td>
<td></td>
</tr>
<tr>
<td>11</td>
<td>GND</td>
<td>Power Ground</td>
<td></td>
</tr>
<tr>
<td>12</td>
<td>GND</td>
<td>Power Ground</td>
<td></td>
</tr>
<tr>
<td>13</td>
<td>B5</td>
<td>Blue Data 5 (MSB)</td>
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<td>14</td>
<td>B4</td>
<td>Blue Data 4</td>
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</tr>
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<td>15</td>
<td>B3</td>
<td>Blue Data 3</td>
<td></td>
</tr>
<tr>
<td>16</td>
<td>GND</td>
<td>Power Ground</td>
<td></td>
</tr>
<tr>
<td>17</td>
<td>B2</td>
<td>Blue Data 2</td>
<td></td>
</tr>
<tr>
<td>18</td>
<td>B1</td>
<td>Blue Data 1</td>
<td></td>
</tr>
<tr>
<td>19</td>
<td>B0</td>
<td>Blue Data 0 (LSB)</td>
<td></td>
</tr>
<tr>
<td>20</td>
<td>GND</td>
<td>Power Ground</td>
<td></td>
</tr>
<tr>
<td>21</td>
<td>G5</td>
<td>Green Data 5 (MSB)</td>
<td></td>
</tr>
<tr>
<td>22</td>
<td>G4</td>
<td>Green Data 4</td>
<td></td>
</tr>
<tr>
<td>23</td>
<td>G3</td>
<td>Green Data 3</td>
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</tr>
<tr>
<td>24</td>
<td>GND</td>
<td>Power Ground</td>
<td></td>
</tr>
<tr>
<td>25</td>
<td>G2</td>
<td>Green Data 2</td>
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</tr>
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<td>26</td>
<td>G1</td>
<td>Green Data 1</td>
<td></td>
</tr>
<tr>
<td>27</td>
<td>G0</td>
<td>Green Data 0 (LSB)</td>
<td></td>
</tr>
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<td>28</td>
<td>GND</td>
<td>Power Ground</td>
<td></td>
</tr>
<tr>
<td>29</td>
<td>R5</td>
<td>Red Data 5 (MSB)</td>
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</tr>
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<td>30</td>
<td>R4</td>
<td>Red Data 4</td>
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</tr>
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<td>R3</td>
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</tr>
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<td>R1</td>
<td>Red Data 1</td>
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<td>R2</td>
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<td>R0</td>
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</tr>
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<td>Power Ground</td>
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<tr>
<td>37</td>
<td>GND</td>
<td>Power Ground</td>
<td></td>
</tr>
<tr>
<td>38</td>
<td>CLK</td>
<td>Clock Signals, Latch Data at the Falling Edge</td>
<td></td>
</tr>
<tr>
<td>39</td>
<td>GND</td>
<td>Power Ground</td>
<td></td>
</tr>
<tr>
<td>40</td>
<td>GND</td>
<td>Power Ground</td>
<td></td>
</tr>
</tbody>
</table>

Fig. 94 Typical 40 pin connector of a 7” LCD without onboard LED driver

As you can see, the signal connection is almost same as that of the other model of panel described before, but Pins 3, 4, 5 and 6 are different. In fact, Pin 3 is not connected like Pin 8, while Pins 4, 5, 6 and 7 all bring the power supply for the LCD (3.3Vdc).

The LED backlight has a separate, independent connector, where the suitable Power must be supplied. The C2 has been designed to supply such power for the LCD’s LED backlight.
6.23.2 **LED_BL CONNECTOR FOR 7” LCD LED BACKLIGHT**

Just aside the LCD7 7” FPC connector there is the LED_BL connector, which is a special 2-pin socket (horizontal) which will fit the LED Backlight connector of the 7” LCD. This is only used when you have to connect a 7” LCD which does not have an onboard LED driver. The onboard LED driver of the C2 (U50) has been designed to feed the correct current for the LED backlight of such 7” panels.

Notice that if you design your assembly so that the C2 will stay as a “sandwich” together with the 7” LCD, the position of this connector has been chosen so that you can directly connect the original LCD backlight cable directly, and this saves costs. See, for example, the assembly below.

If you need to stuff the C2 far away from the LCD, you need special extension cables (see dedicated chapter which follows).
6.24 TOUCH (BOTTOM) CONNECTORS FOR 4W TOUCH SCREEN

There are 3 connectors for easy instant connection of a 4W (4 Wire) touch-screen. They are placed at bottom side of the board, opposite side of the SD sockets.

![Diagram showing the connectors](image)

**Fig. 97 The 3 types of 4W touch-screen connectors: 2.54mm header, 1.0mm and 0.5mm FPC**

Three connectors have been provided in order to accommodate any typical solution coming from the bonded touch of the 7” panel: from left to right of the above image you see the 2.54mm header, the FPC connector with 1.0mm pitch and the FPC connector with 0.5mm pitch. They are wired in parallel. You will choose the one which fits the cable of the resistive touch-screen which you are using.

![Diagram showing the connectors for FPC cable](image)

**Fig. 98 The 4W touch-screen connectors for FPC cable: 1.0mm and 0.5mm FPC**

The X/Y assignment can be changed thanks to an array of micro-resistors. The default configuration connects the following:

1. X negative  →  TOUCH-1
2. X positive  →  TOUCH-3
3. Y negative  →  TOUCH-2
4. Y positive  →  TOUCH-4
Also the 90° pin header **TOUCH-254** has a default configuration:

![Diagram of TOUCH-254 pin header]

**Fig. 99** The 4W touch-screen connector for 2.54mm flat cable

### 6.24.1 EXTENSION CABLES

CJB can provide suitable extension cables for both the 4W touch and the LED backlight, in case you need to place the C2 away of the LCD panel. For a minimum quantity, the extension cable length can be customized.

![Extension Cable for LCD Backlight](image1)

**Fig. 100** Extension Cable for LCD Backlight

![Extension Cable for 4W Touch](image2)

**Fig. 101** Extension Cable for 4W touch
6.25 SD1 (BOTTOM SIDE)  
**uSD MEMORY CARD SOCKET**

This socket can host one µSD flash memory card positioned under the right edge of the board in a plug-plug spring socket. The µSD is self-recognized and can be plugged-in or removed even if the C2 board is powered on.

![Fig. 102  µSD Flash Card Socket (Bottom Side)](image1)

6.26 SD2 (BOTTOM SIDE)  
**SD MEMORY CARD SOCKET**

This socket can host one SD flash memory card positioned under the right edge of the board in a plug-plug spring socket. The SD is self-recognized and can be plugged-in or removed even if the C2 board is powered on. The SD is managed as mass memory “hard disk like” device.

![Fig. 103  SD Flash Card Socket (Bottom Side)](image2)

We suggest using the µSD for the Operating System, and the SD for data logging.
7 HOW TO MOUNT (Panel/Wall)

The Panel Mount version of the TouchMover-A8 is easily mounted on a hole in the panel.

While the Wall-Mount version requires a hole in the wall:
7.1 PANEL MOUNT
If the TouchMover-A8 has to be installed onto a panel (“Panel Mount”) just use the supplied special screw-hooks at the rear, to PULL the system against the front panel:

The O-ring gasket in the groove (rear of the front bezel) will make tight IP-65 protection between the TouchMover-A8 front bezel and the panel.
7.2 WALL MOUNT SOLUTION
When the TouchMover-A8 has to be wall-mounted, at first you have to make a hole in the wall and put in there the special wall mount box:

You can see the box is CLOSED by the special cover which protects the box against cement or mortar dirt. Now you can remove the cover and you can see the wall mount box cemented in the wall:

Notice the snap-out holes at side (for cable passing) and the brackets for keeping the box in place when cementing it inside the wall.
Now you can get the special Wall-Mount frame:

![Wall-Mount frame image]

and mount it to the cemented box:

![Cemented box image]
So at last you get:

Now the wall is ready to host the system, which will be attached by MAGNETS to the frame “A” and will be easily positioned perfectly perpendicular, thanks to the panning pivot “B”.

Following page shows how to make the TouchMover-A8 perfectly horizontal even if the wall box is not perfectly perpendicular. The system stays matched to the wall thanks to 3 magnets on the rear of the front bezel.
The system stays matched to the wall thanks to 3 magnets on the rear of the front bezel.

And thanks to the upper central **PIVOT**, and enough room between system and wall mount frame, you can adjust the system for having it 100% perpendicular, just you can tilt a bit to make it horizontal.